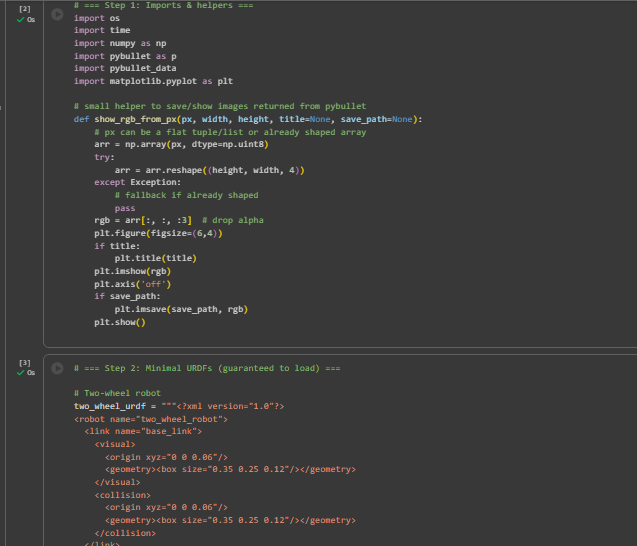
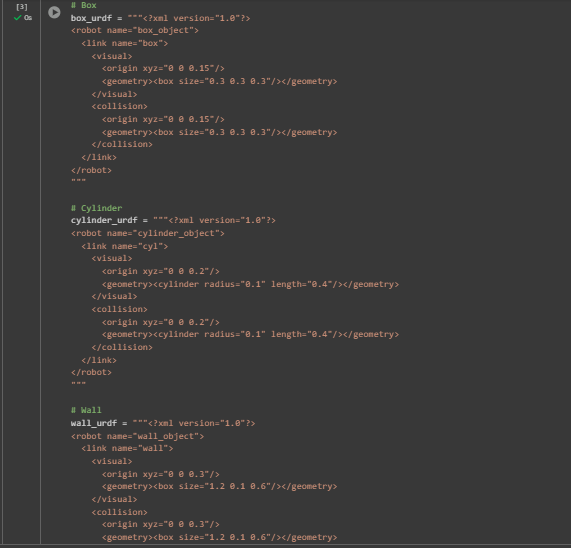
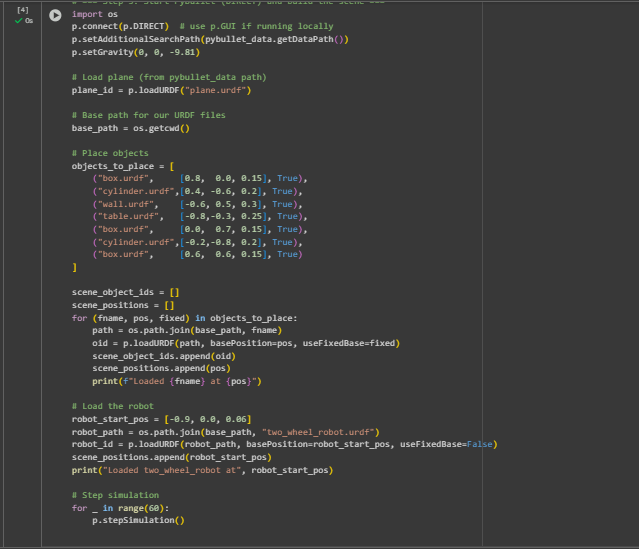
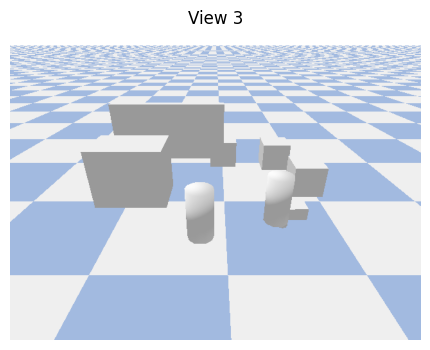
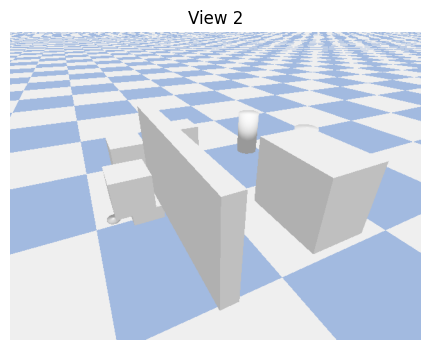
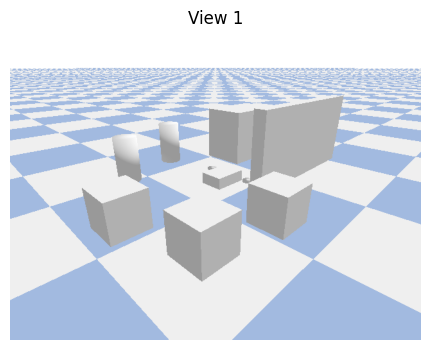
**Task 1. PyBullet World Building with URDFs**









**Task 2. Autonomous Robot Simulation with ROS2 (TheConstruct.ai)**

